REMARKS

Claims 34, 35, 38, 41 and 42 were rejected under 35 U.S.C. § 112, second paragraph as being indefinite. New claims 50-54 are substituted herewith to traverse the indefiniteness rejection lodged against the remaining claims.

Claim 50 makes it clear that successive segments of the web are held at the web processing station, and that while being held, the segment of the web is allowed to shift relative to the remaining portion of the web as necessary to obtain accurate alignment of the segment of the web with processing components with the web processing station. Claim 50 further calls for the step of continuing to hold the held segment of the web while the segment is adjusted along the X axis web feed direction, the Y axis direction transverse to the X axis, about θ axis of rotation, or simultaneous combinations of such adjustments. The meaning of X axis, Y axis and θ axis motions is explained in detail in the Specification and illustrated in the Drawings. Therefore, there is clear antecedent basis for the X, Y and θ motion limitations of claim 50.

Claim 51 is directed to the method of die cutting of the segment of the web and the claim calls for die cutting elements which are located at the die cutting station to die cut the segment while accurately positioning relative to the die cutting elements. Thus, claim 51 is definite in all respects.

It is submitted that claims 50-54 not only meet the requirements of paragraph 2 of 35 U.S.C. § 112 but are also patentable under §§ 102 and 103.

Attached hereto is a marked-up version of the changes made to the specification and claims by the current amendment. The attached page is captioned **"Version with markings to show changes made."**

REMARKS

Claims 34, 35, 38, 41 and 42 were rejected under 35 U.S.C. § 112, second paragraph as being indefinite. New claims 50-54 are substituted herewith to traverse the indefiniteness rejection lodged against the remaining claims.

Claim 50 makes it clear that successive segments of the web are held at the web processing station, and that while being held, the segment of the web is allowed to shift relative to the remaining portion of the web as necessary to obtain accurate alignment of the segment of the web with processing components with the web processing station. Claim 50 further calls for the step of continuing to hold the held segment of the web while the segment is adjusted along the X axis web feed direction, the Y axis direction transverse to the X axis, about θ axis of rotation, or simultaneous combinations of such adjustments. The meaning of X axis, Y axis and θ axis motions is explained in detail in the Specification and illustrated in the Drawings. Therefore, there is clear antecedent basis for the X, Y and θ motion limitations of claim 50.

Claim 51 is directed to the method of die cutting of the segment of the web and the claim calls for die cutting elements which are located at the die cutting station to die cut the segment while accurately positioning relative to the die cutting elements. Thus, claim 51 is definite in all respects.
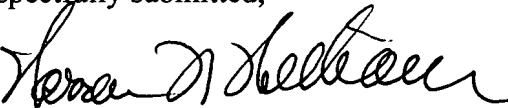
It is submitted that claims 50-54 not only meet the requirements of paragraph 2 of 35 U.S.C. § 112 but are also patentable under §§ 102 and 103.

Attached hereto is a marked-up version of the changes made to the specification and claims by the current amendment. The attached page is captioned **"Version with markings to show changes made."**

Any additional fee which is due in connection with this amendment should be applied against our Deposit Account No. 19-0522.

In view of the foregoing, a Notice of Allowance appears to be in order and such is courteously solicited.

Respectfully submitted,

By _____
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ATTORNEYS FOR APPLICANT(S)

(Docket No. 25520-B)

VERSION WITH MARKINGS TO SHOW CHANGES MADE

The present title in the Specification has been deleted and the following new title is substituted therefor:

 METHOD FOR SIMULTANEOUS X, Y AND θ REGISTRATION OF SEGMENT OF CONTINUOUS WEB WITH A PROCESSING STATION [WEB OR SHEET-FED APPARATUS HAVING HIGH-SPEED MECHANISM FOR SIMULTANEOUS X, Y AND θ REGISTRATION AND METHOD]